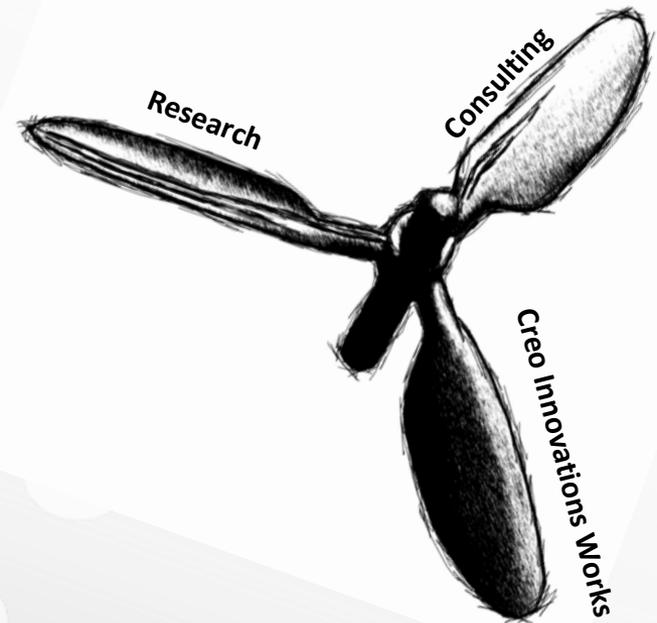


A reduction method for the vibro-acoustic problem including poroelastic material using interface-dependent Lanczos vectors

SAPEM 2014, STOCKHOLM

Peter Davidsson, Creo Dynamics AB
Göran Sandberg, Lund University



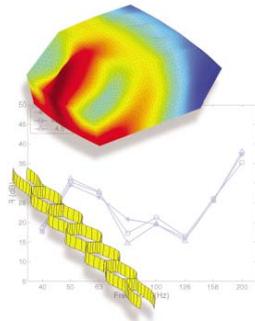
Introduction



KK-stiftelsen ><

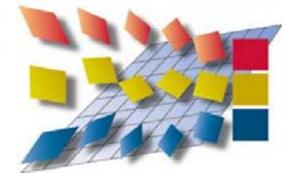
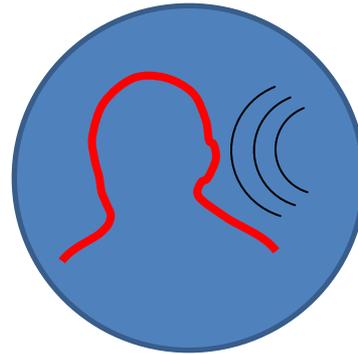


LUND
UNIVERSITY



**STRUCTURE-ACOUSTIC ANALYSIS;
FINITE ELEMENT MODELLING AND
REDUCTION METHODS**

PETER DAVIDSSON



CALFEM
A FINITE ELEMENT TOOLBOX
Version 3.4

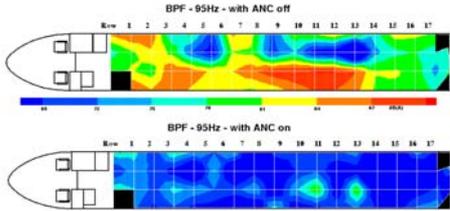
P-E AUSTRELL, O DAHLBLOM, J LINDEMANN,
A OLSSON, K-G OLSSON, K PERSSON, H PETERSSON,
M RISTINMAA, G SANDBERG, P-A WERNBERG



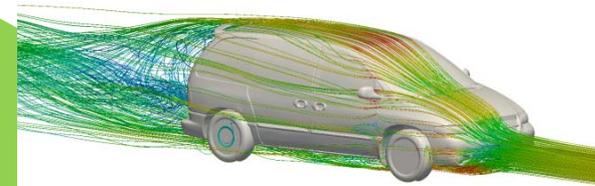
Structural
Mechanics

Doctoral Thesis

Active Noise Control in Saab 2000
350 KTAS FL300 950rpm



Active noise control



Aero-acoustic CFD

Propeller/engine noise

Flow induced noise

Transfer path

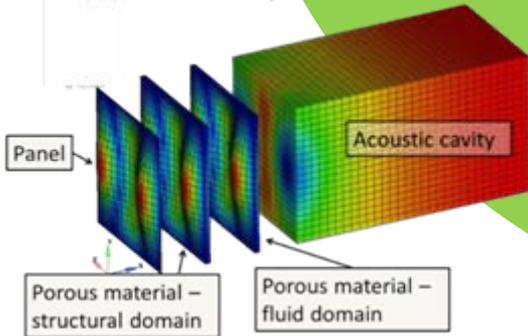
Advanced materials

Sound absorbing material

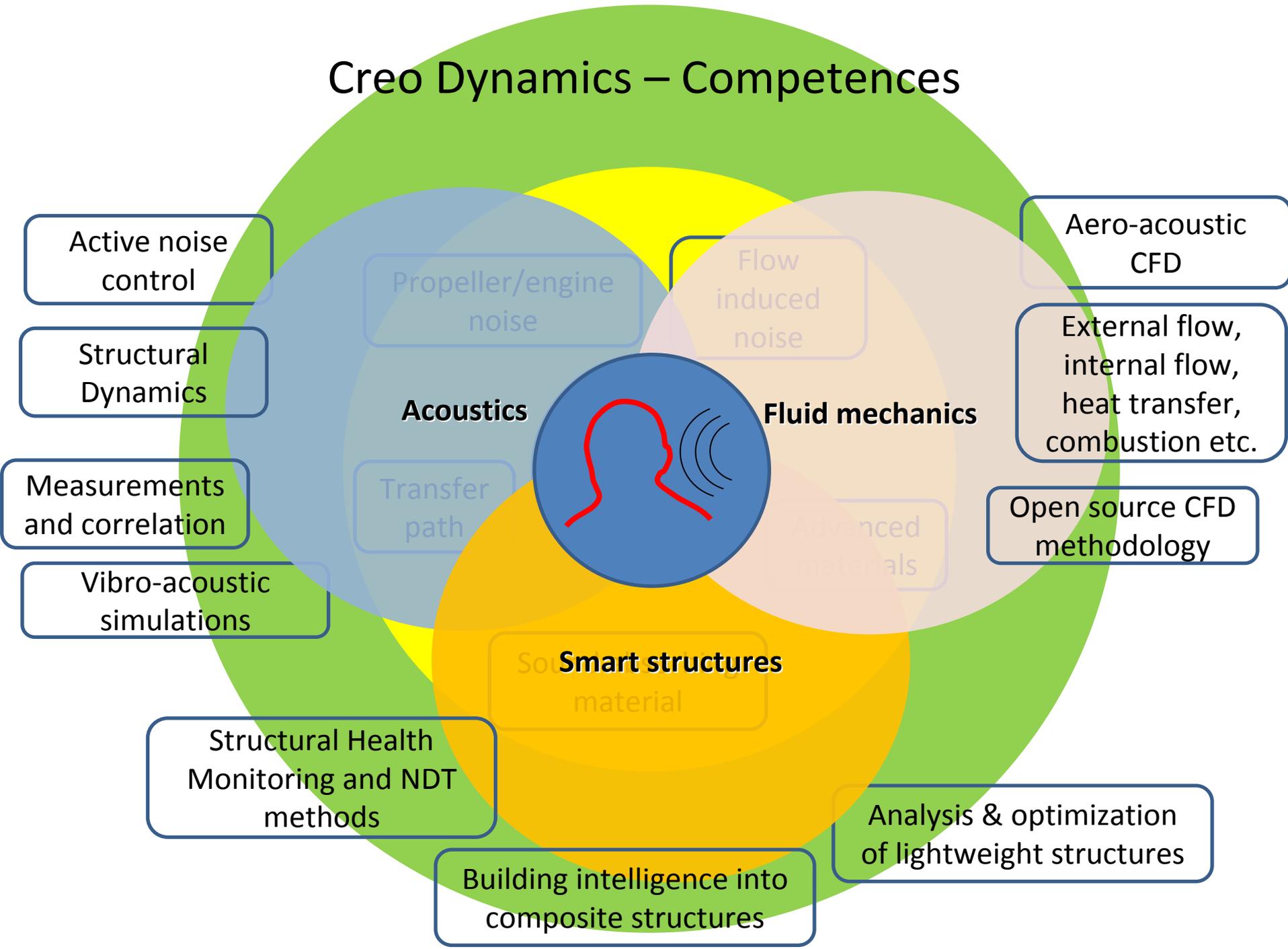
Vibro-acoustic simulations

Analysis & optimization of lightweight structures

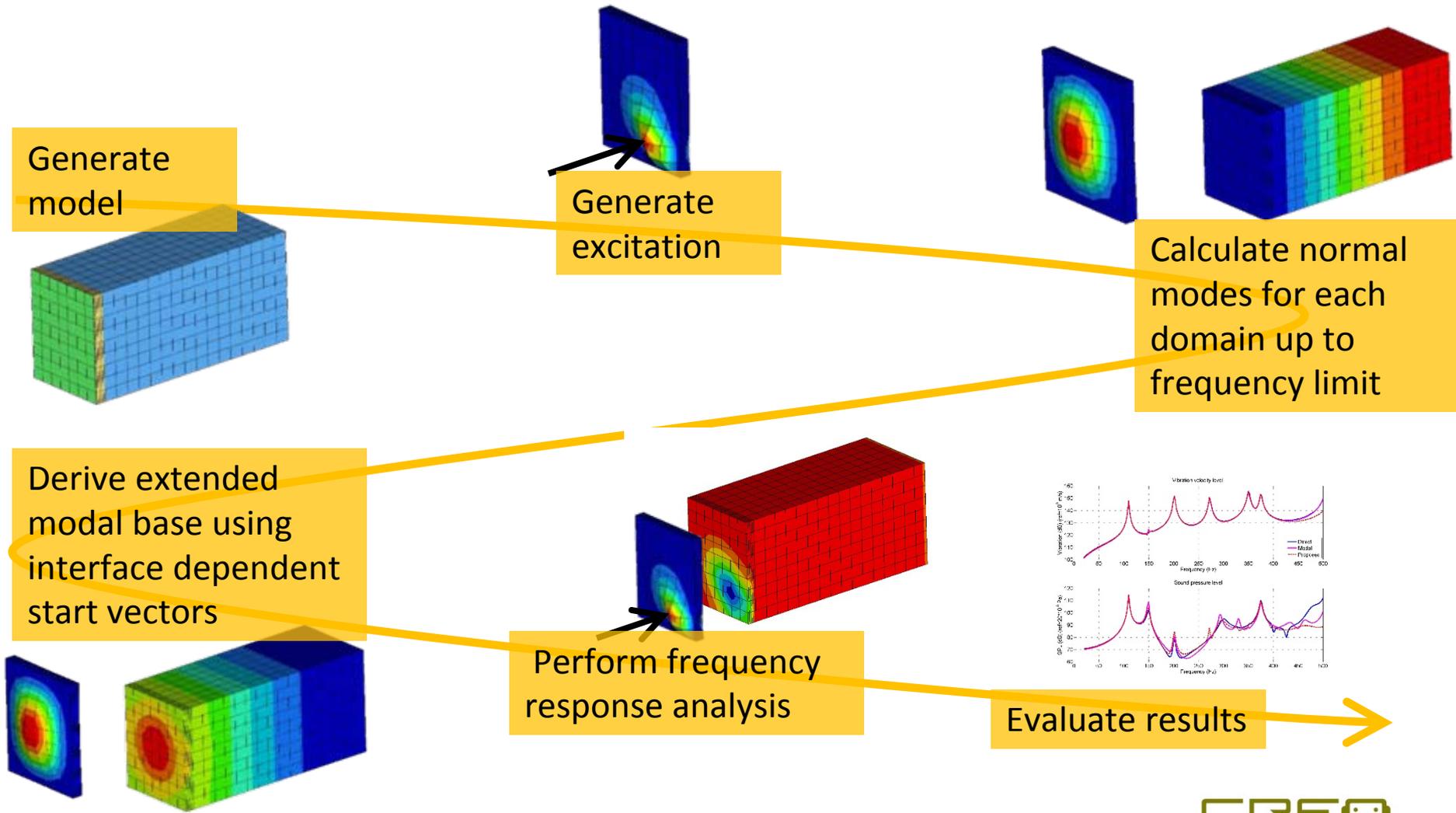
Biot's formulation for porous material



Creo Dynamics – Competences



Analysis procedure



Structure-acoustic analysis

- Vibro-acoustic problem

$$\begin{bmatrix} -\omega^2 \mathbf{M}_s + \mathbf{K}_s & -\mathbf{H} \\ -\omega^2 \mathbf{H}^T & -\omega^2 \mathbf{M}_p + \mathbf{K}_p \end{bmatrix} \begin{bmatrix} \mathbf{d} \\ \mathbf{p} \end{bmatrix} = \begin{bmatrix} \mathbf{f}_s \\ \mathbf{f}_p \end{bmatrix}$$

- Porous material using \mathbf{u}/p formulation

$$\begin{bmatrix} -\omega^2 \mathbf{M}_{ss} + \mathbf{K}_{ss} & -\mathbf{C}_{sp} \\ -\omega^2 \mathbf{C}_{sp}^T & -\omega^2 \mathbf{M}_{pp} + \mathbf{K}_{pp} \end{bmatrix} \begin{bmatrix} \mathbf{d} \\ \mathbf{p} \end{bmatrix} = \begin{bmatrix} \mathbf{f}_{bs} \\ \mathbf{f}_{bp} \end{bmatrix}$$

- Coupling force terms

$$\mathbf{f}_{p \rightarrow s} = -\mathbf{H} \mathbf{p}$$

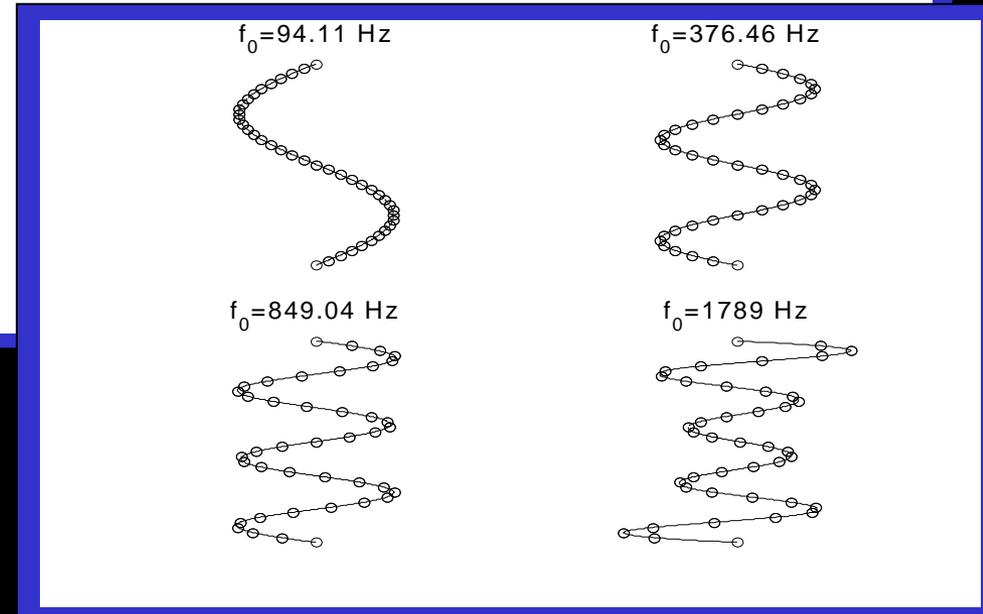
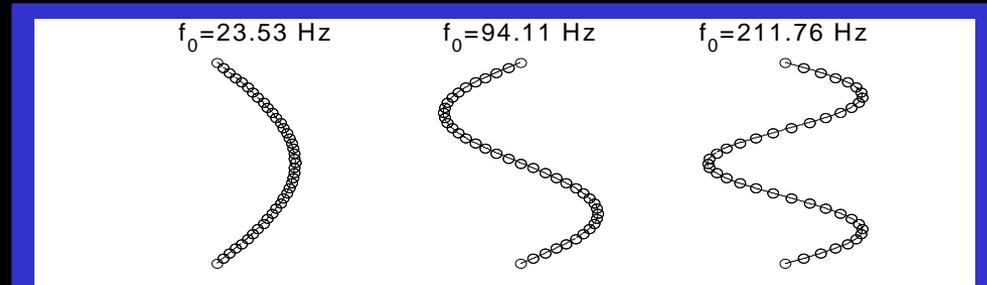
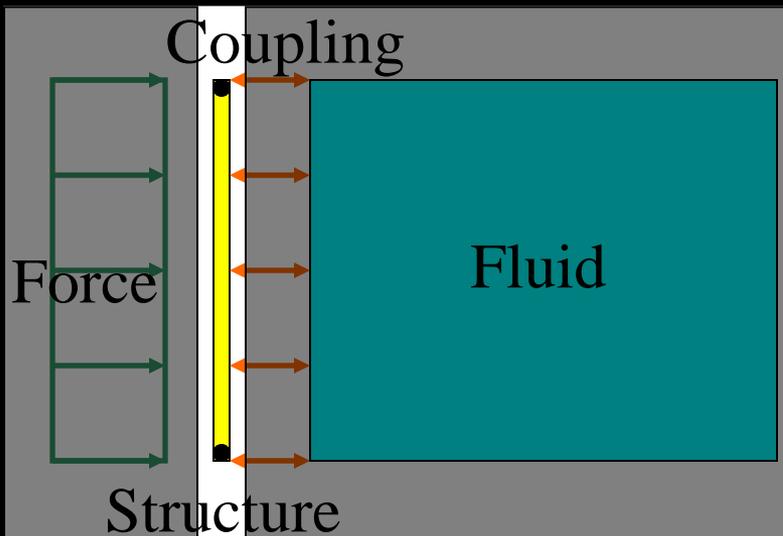
$$\mathbf{f}_{s \rightarrow p} = -\mathbf{C}_{sp} \mathbf{p}$$

$$\mathbf{f}_{s \rightarrow p} = -\omega^2 \mathbf{H}^T \mathbf{d}$$

$$\mathbf{f}_{s \rightarrow p} = -\omega^2 \mathbf{C}_{sp}^T \mathbf{d}$$

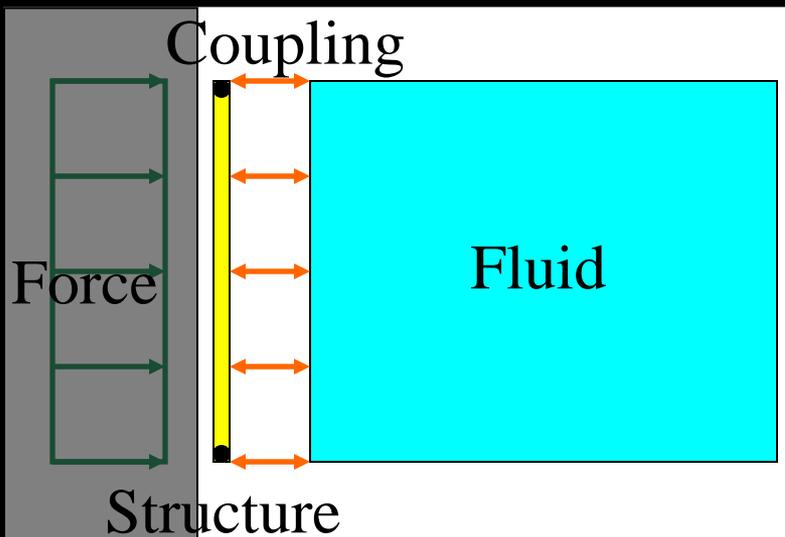
Lanczos vectors

- Load dependent start vector in eigenvalue analysis
 - Random force \rightarrow all modes
 - Actual force \rightarrow important modes



Lanczos vectors

- Calculate the start vectors for each domain from
 - the pressure distribution of the fluid domain at the interface boundary
 - the displacement of the structure at the interface
- Where to get this information?



Analysis procedure

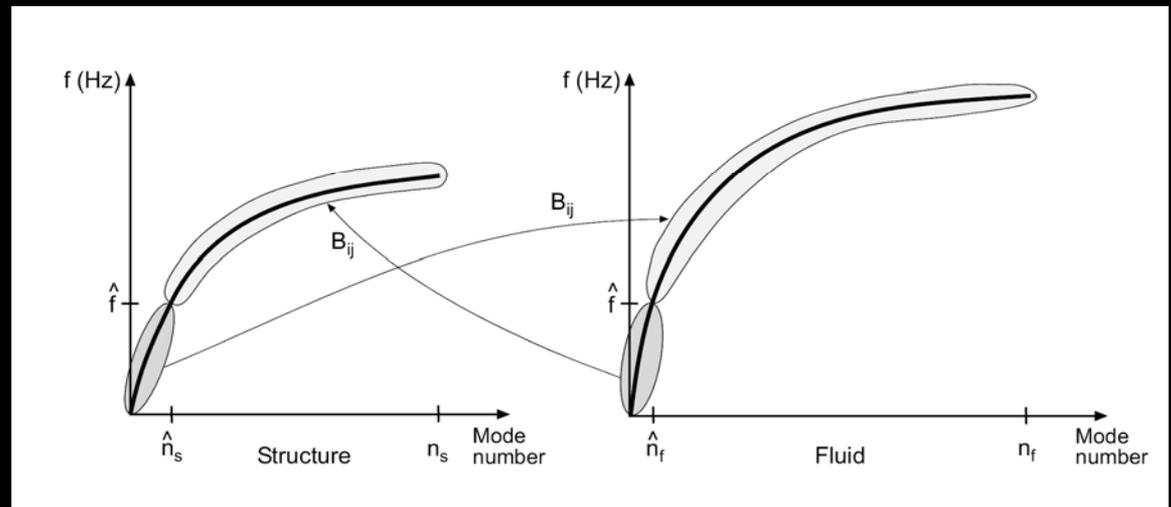
- Calculate the uncoupled modes up to the frequency limit of interest

$$\langle \hat{\Lambda}_S, \hat{\Phi}_S \rangle \quad \langle \hat{\Lambda}_F, \hat{\Phi}_f \rangle$$

- Calculate the interface vectors

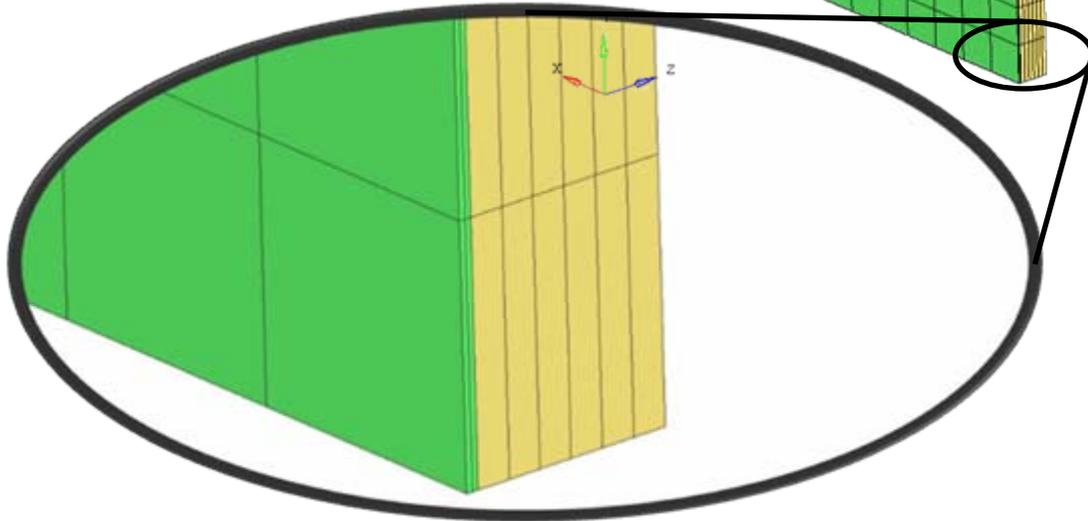
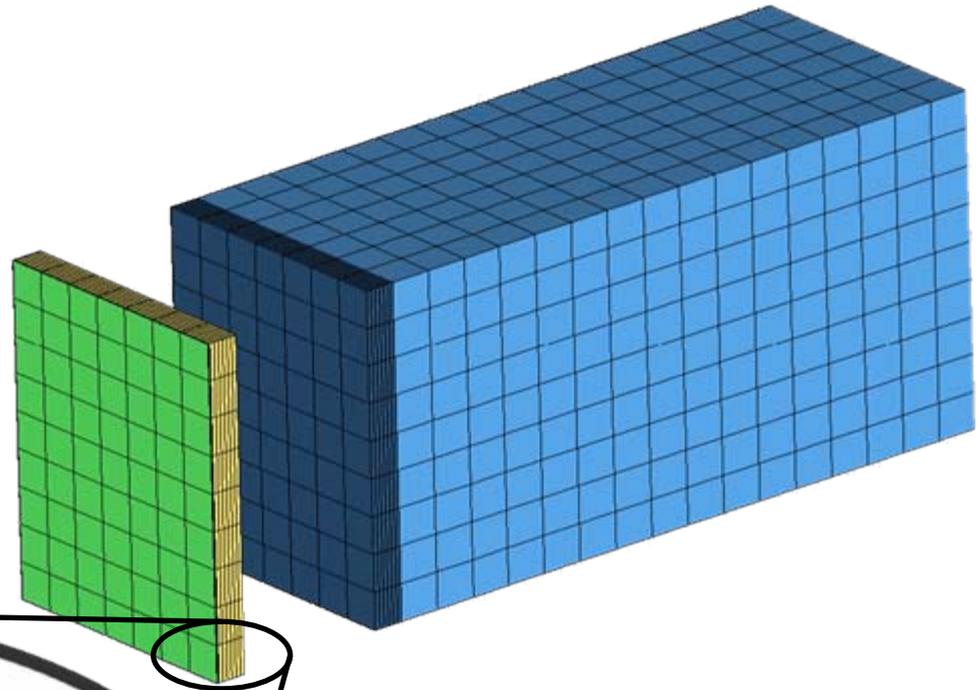
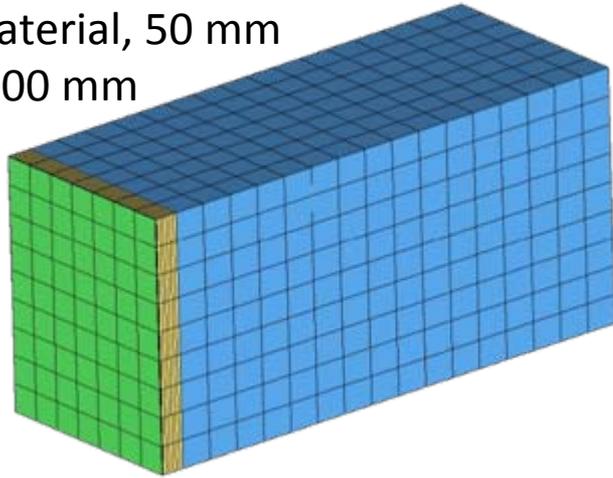
$$\mathbf{r}_F = \mathbf{H}_{SF} \hat{\Phi}_F \quad \mathbf{r}_S = \mathbf{H}_{SF}^T \hat{\Phi}_S$$

- Derive a number of Lanczos vectors for each interface vector

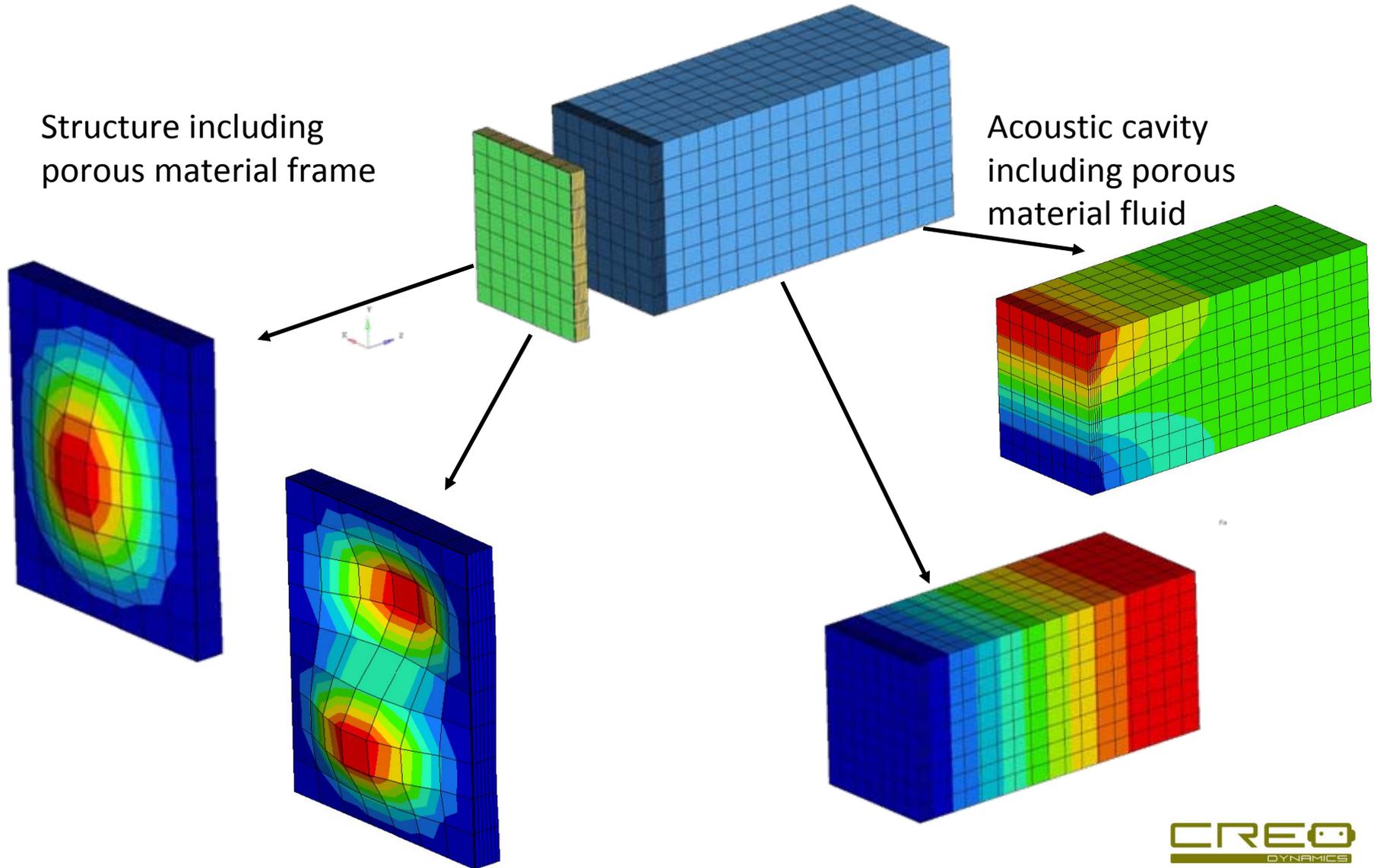


Box model

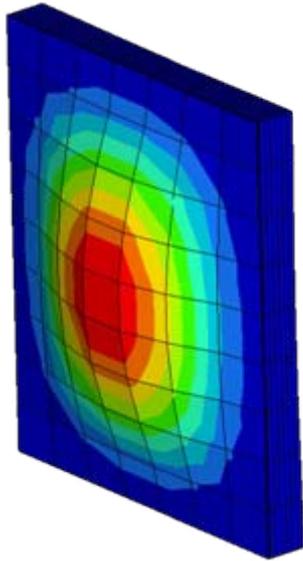
Aluminum panel, 3 mm
Porous material, 50 mm
Cavity, 1100 mm



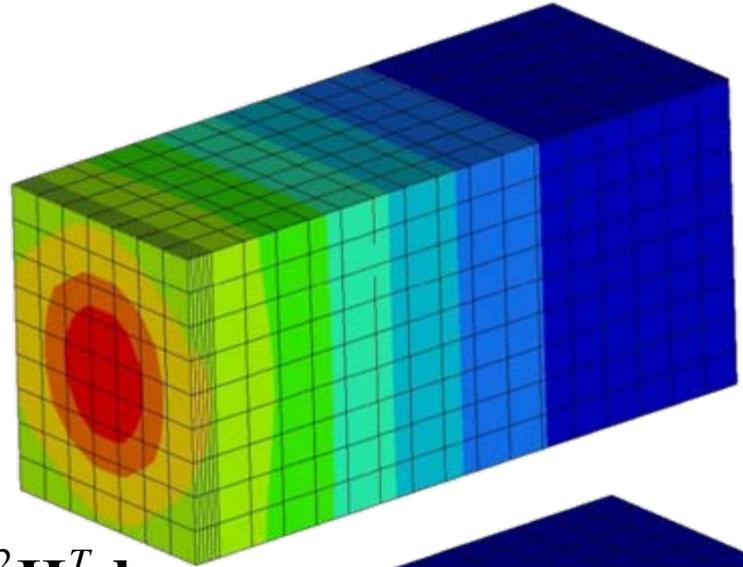
Uncoupled modes



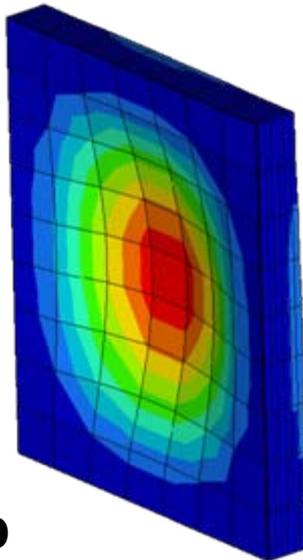
Start vectors



$$\mathbf{f}_{p \rightarrow s} = -\mathbf{H}\mathbf{p}$$

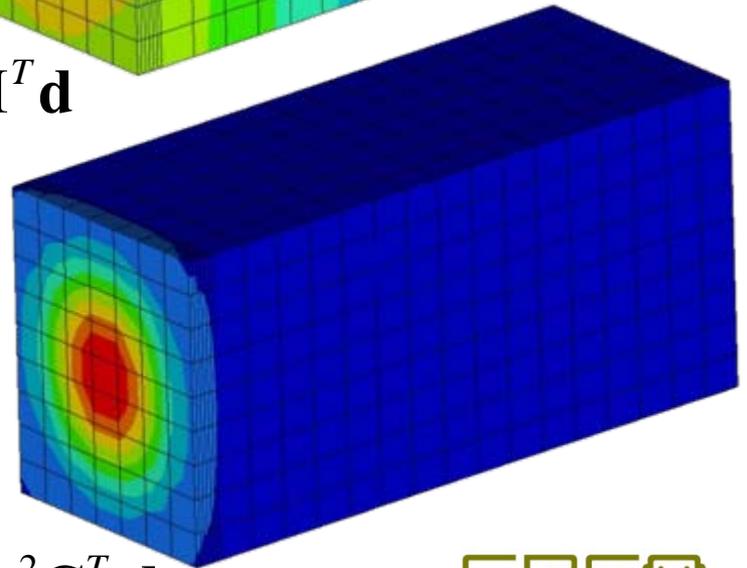


$$\mathbf{f}_{s \rightarrow p} = -\omega^2 \mathbf{H}^T \mathbf{d}$$



$$\mathbf{p} = \Phi_f \xi_f$$

$$\mathbf{d} = \Phi_s \xi_s$$



$$\mathbf{f}_{s \rightarrow p} = -\omega^2 \mathbf{C}_{sp}^T \mathbf{d}$$

$$\mathbf{f}_{s \rightarrow p} = -\mathbf{C}_{sp} \mathbf{p}$$

Frequency response analysis

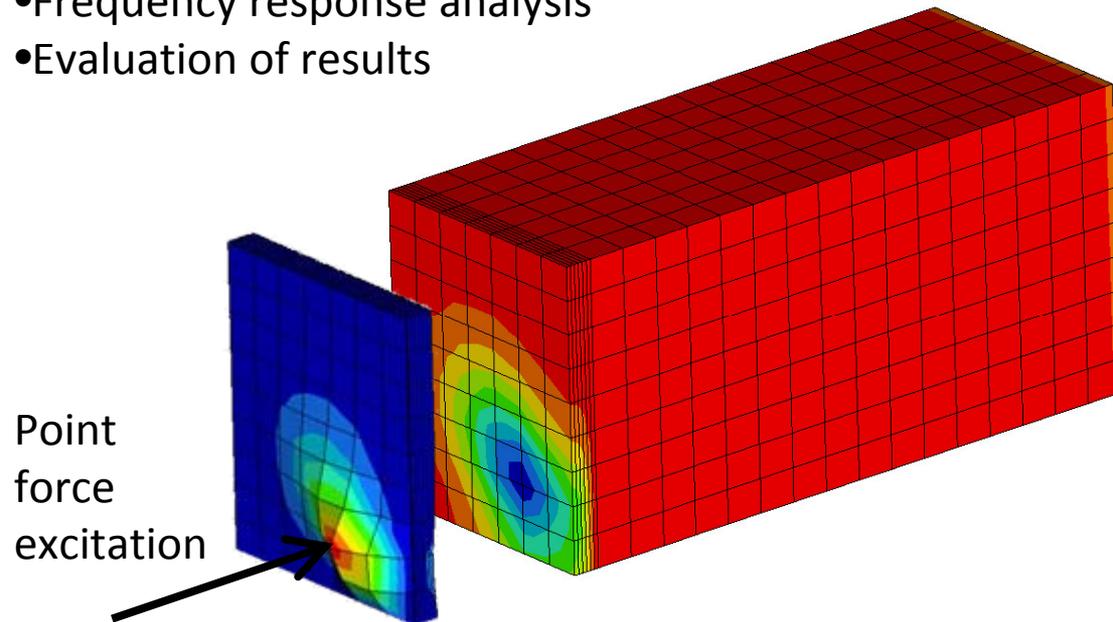


Procedure:

- Uncoupled modes
- Start vectors
- Interface dependent Lanczos vectors – extended modal base
 - Derived in iterative procedure based on the start vectors
- Modal reduction of the vibro-acoustic problem.
- Frequency response analysis
- Evaluation of results

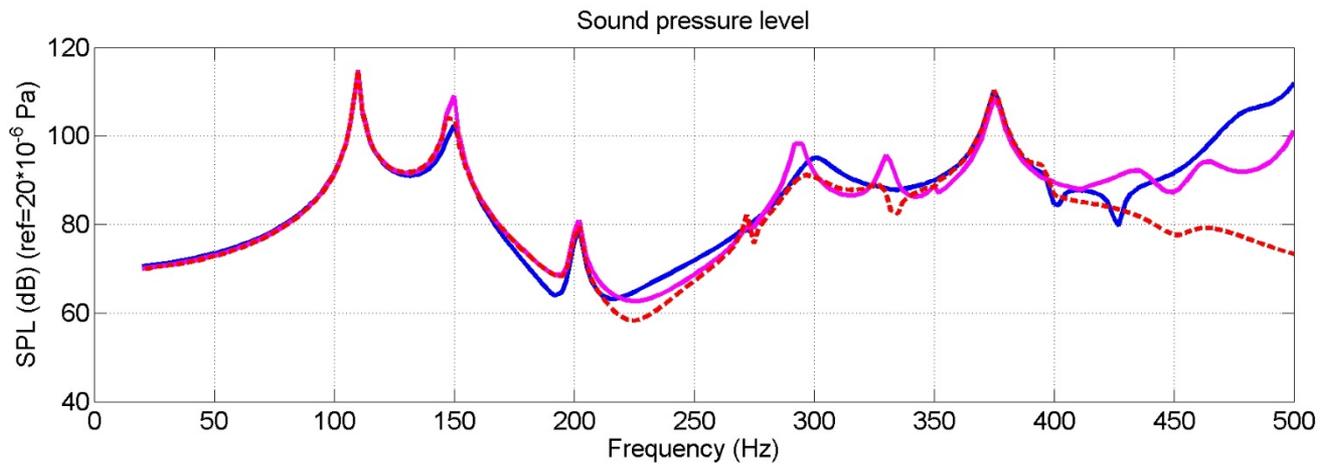
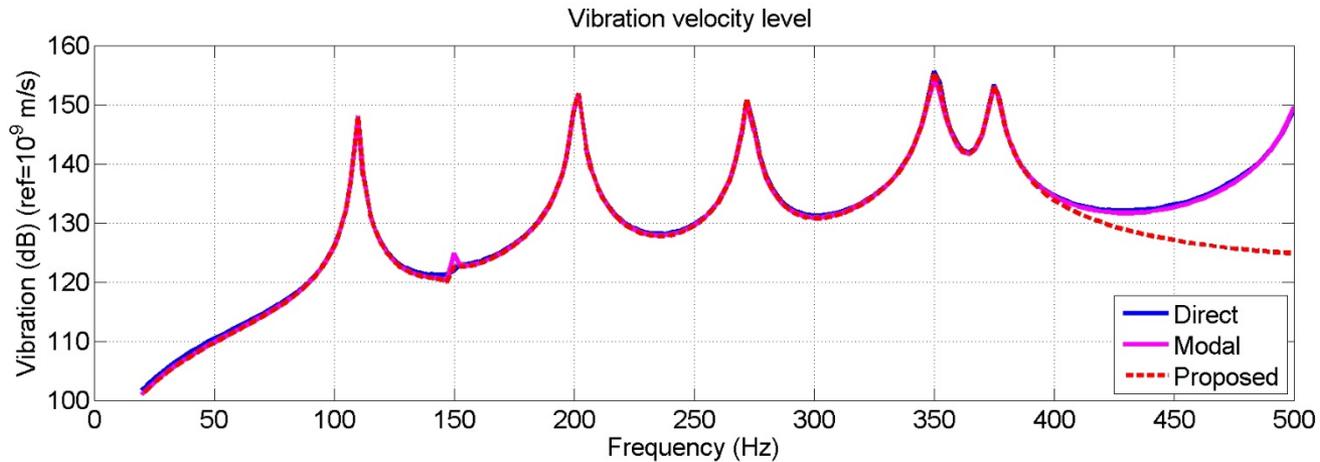
Results derived using:

- Direct solution (Direct)
- Modal reduction using uncoupled modes up to twice the frequency range of interest (Modal)
- Modal reduction using extended base with interface dependent Lanczos vectors (Proposed)

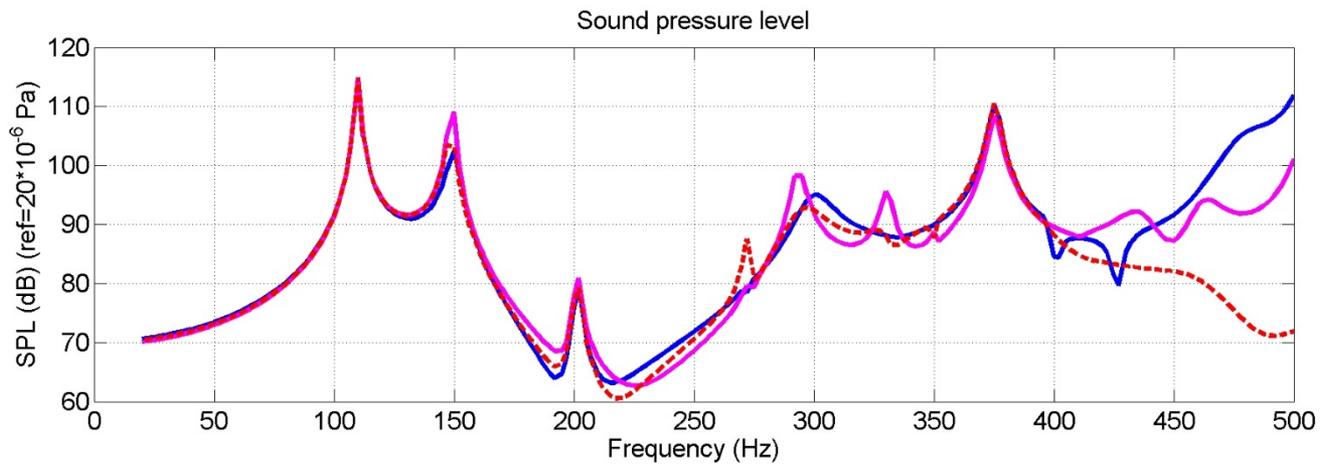
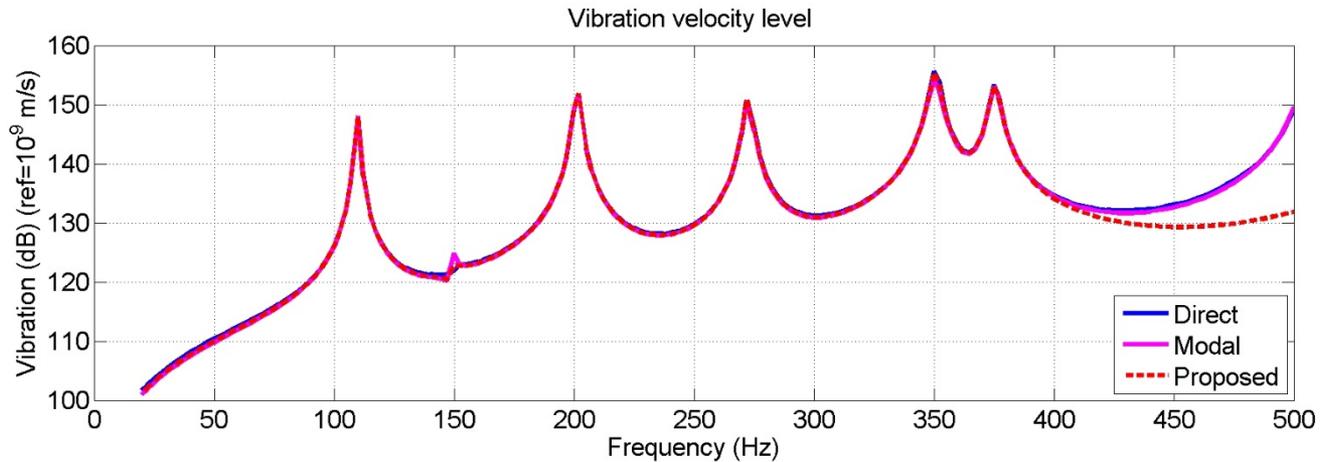


- Frequency sweep: 20 –500 Hz
- Evaluate:
 - Mean vibration level
 - Mean SPL

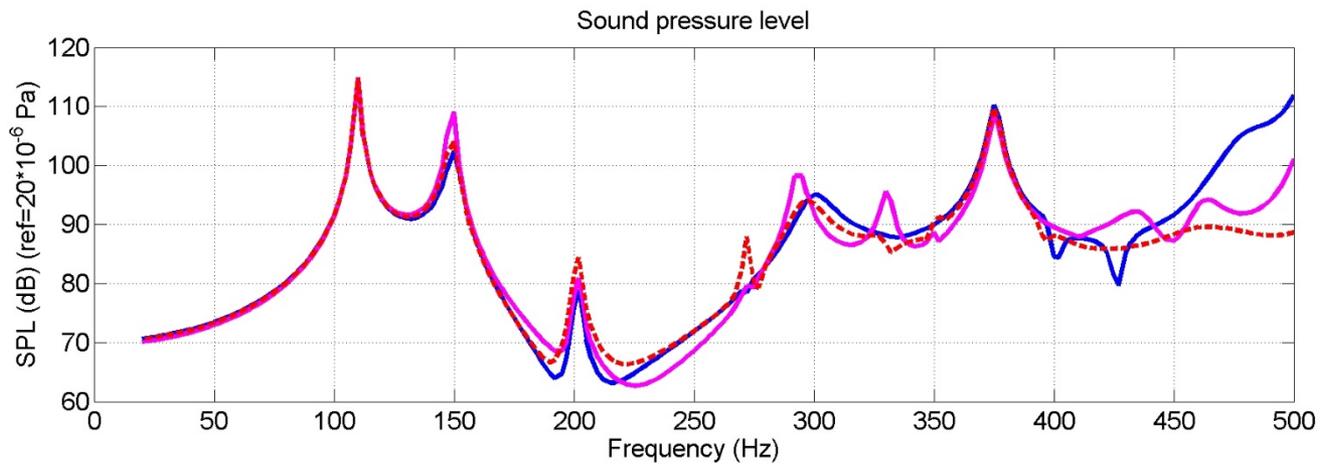
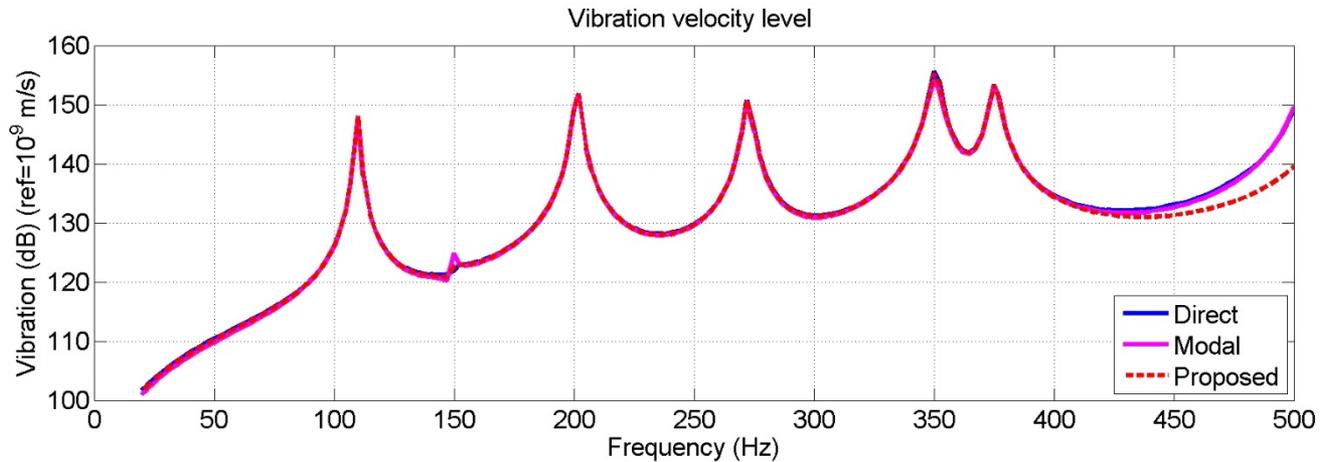
Frequency response result, One iteration



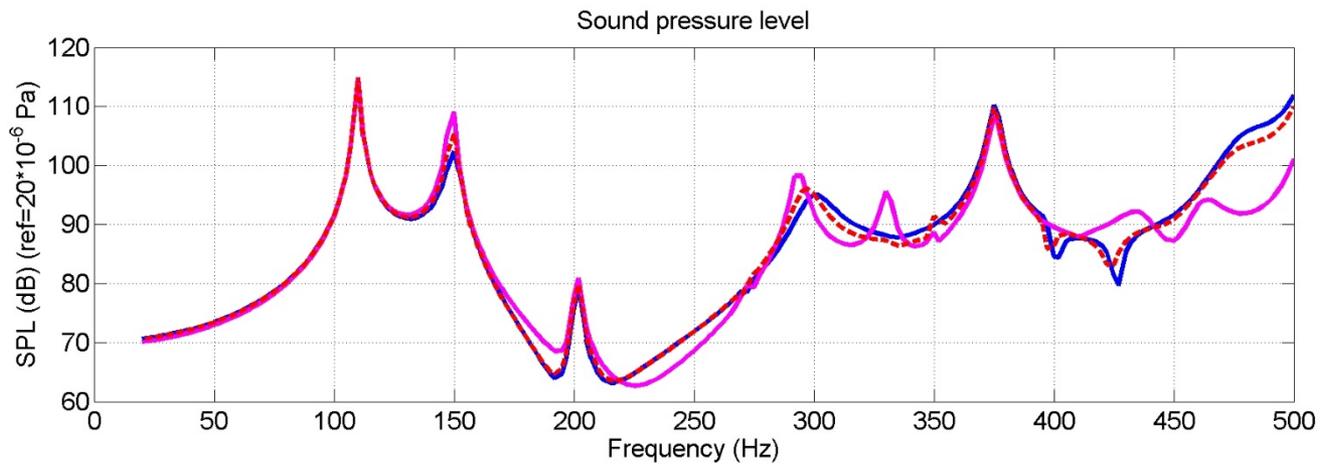
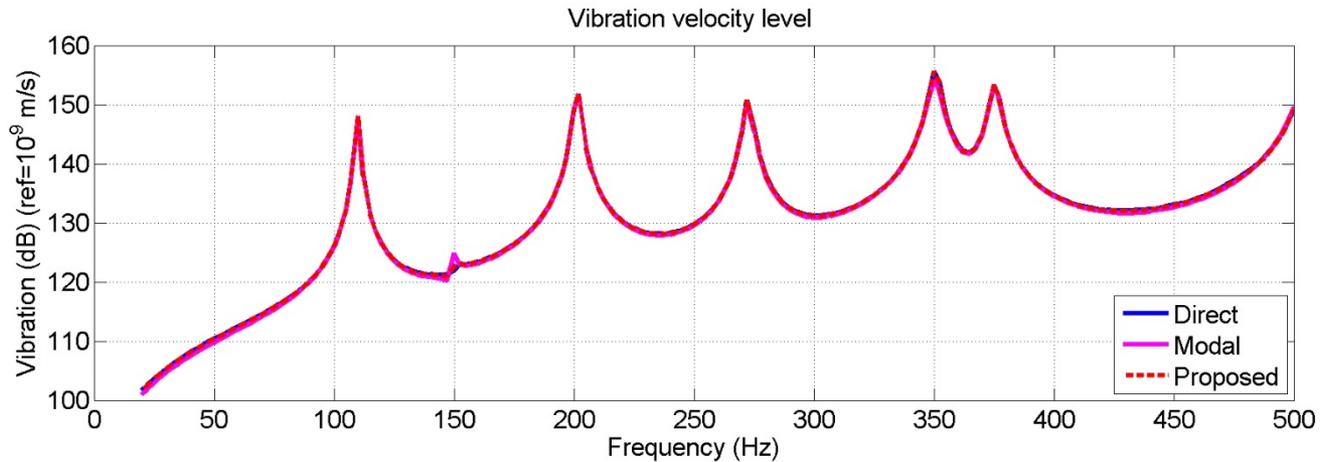
Frequency response result, Two iterations



Frequency response result, Four iterations



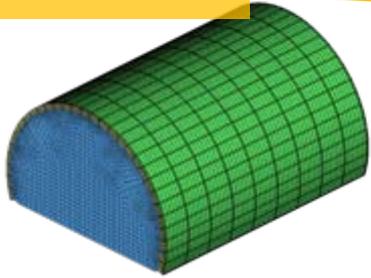
Frequency response result, Eight iterations



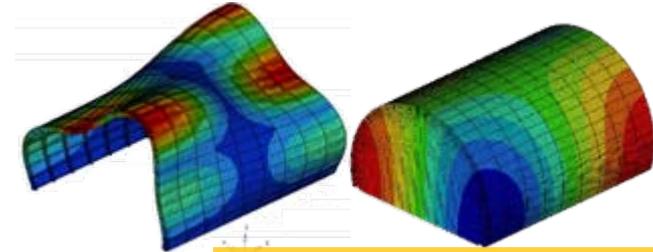
Analysis procedure, Small “industrial” problem

Structural dofs: ~500 000
Acoustic fluid dofs: ~180 000

Generate model



Generate excitation

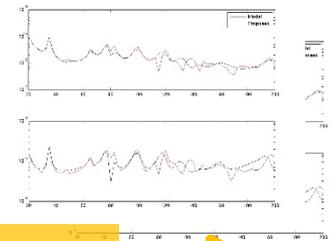


Calculate normal modes for each domain up to frequency limit

Derive extended modal base using interface dependent start vectors

Perform frequency response analysis

Evaluate results

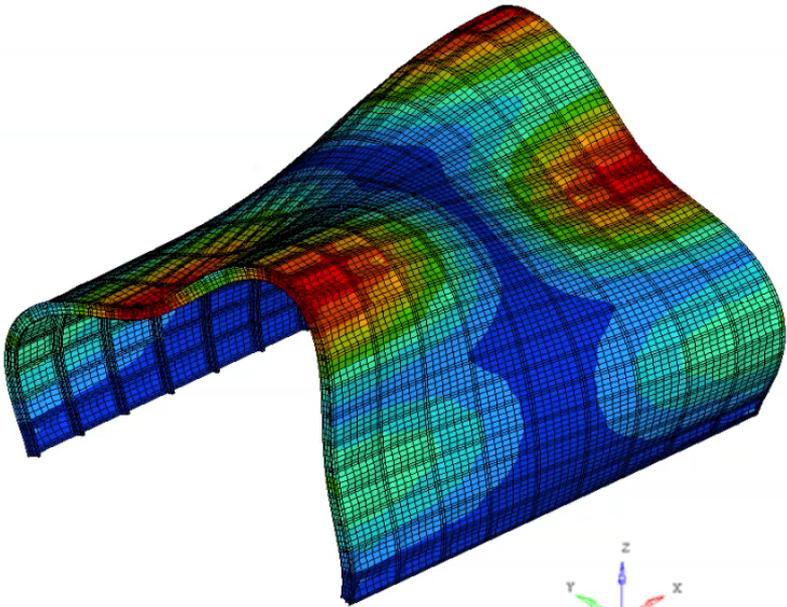


Analysis procedure , Small “industrial” problem

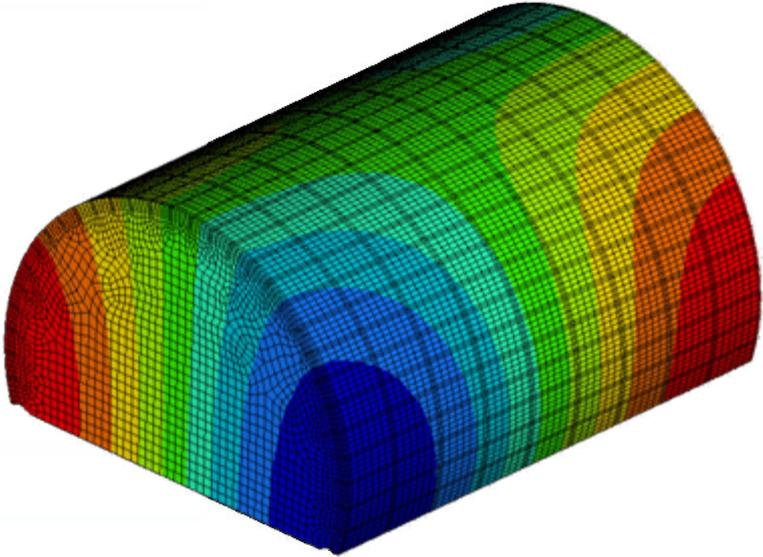


Frequency = 15.636 Hz Mode =

ot
(Mag)
ystem
01
01
02
02
02
02
02
02
02
+00
||
DE-01
5
DE+00
2



Frequency = 80.153 Hz Mode = 4

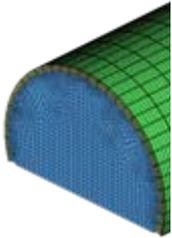


response analysis

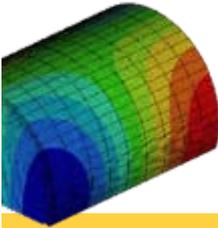
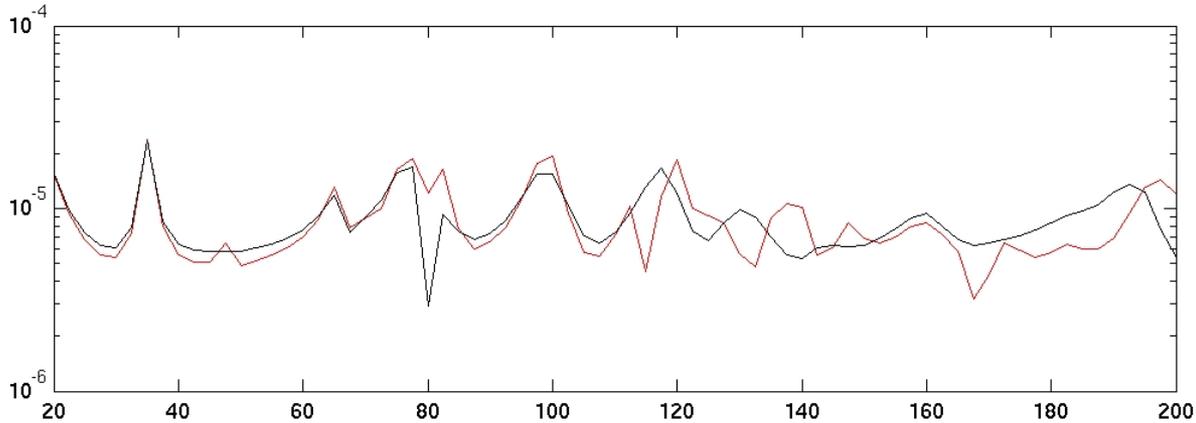
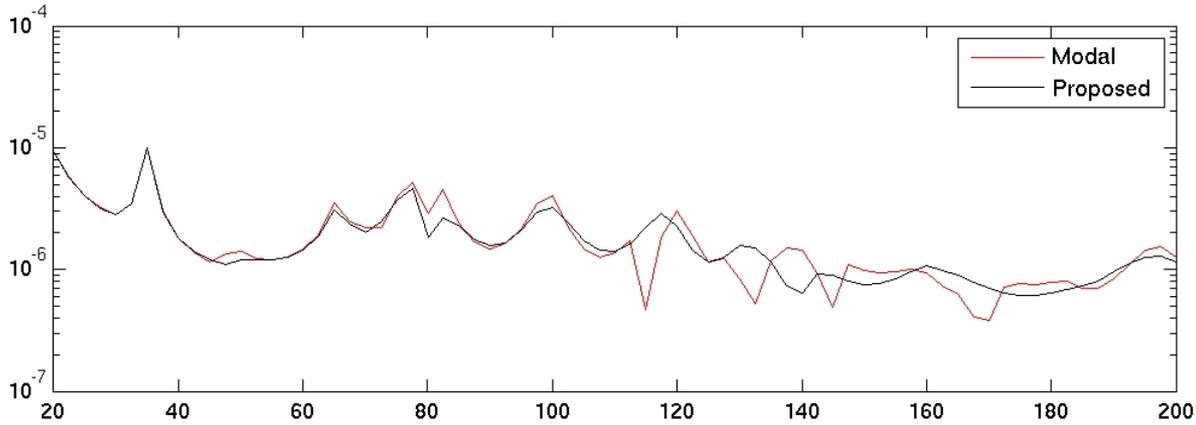
Evaluate results 

Analysis procedure , Small “industrial” problem

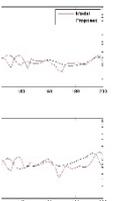
Generate model



Derive external modal basis interface and start vectors



normal
each
to
limit



Conclusions

- Simulation using normal modes works well for this vibro-acoustic problem
- Box problem gives converging results with increased number of modes
- Typical small industry type of vibro-acoustic problem needs further evaluation, but first results are promising

Creo Dynamics contacts

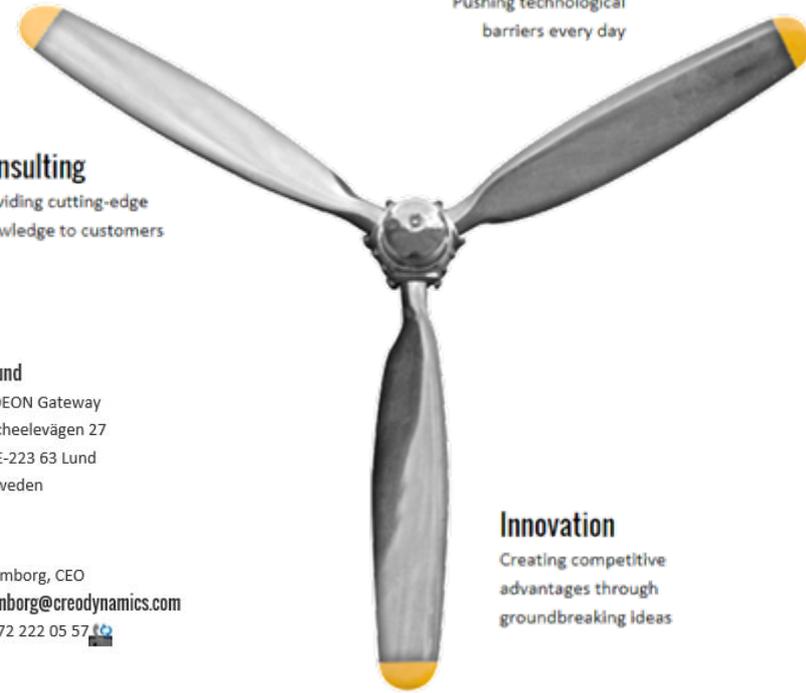


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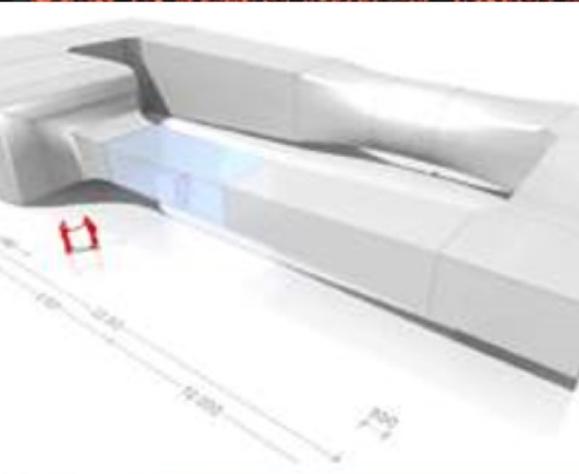
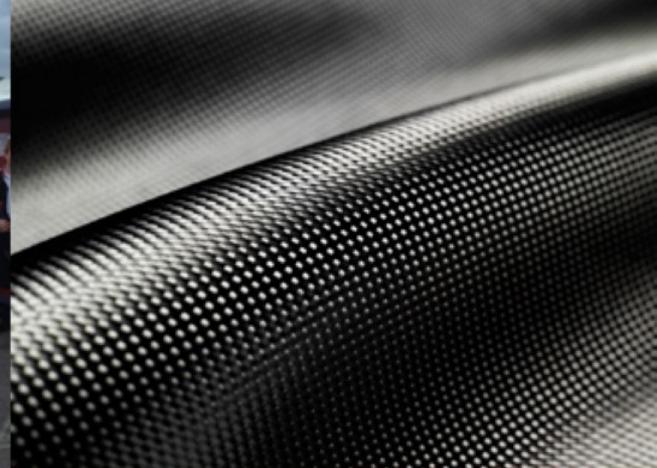


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